

Levin's Lower Bound Theorem

Theorem: Let f be a total recursive function. Then there exists a total recursive function g such that, for any space function s such that $s(x) = \Omega(\log |x|)$

$$f \in \text{DSPACE}(s) \iff s = \Omega(g)$$

Proof: Let f be given. Let $C = \{s : s \text{ is a space function and } f \in \text{DSPACE}(s)\}$. Our goal is to build a total recursive g so that for any space function s such that $s(x) = \Omega(\log |x|)$, $s \in C \iff s = \Omega(g)$.

Our first step will be to characterize C . We will build a sequence of functions p_1, p_2, \dots such that:

- (1) $\forall i \ p_i \in C$.
- (2) s a space function in $\Omega(\log) \implies [s \in C \iff \exists i \ s = \Omega(p_i)]$ (and in fact, for all large i , $[M_i$ runs in space s and computes $f] \implies s = \Omega(p_i)$).
- (3) The function $\langle i, x \rangle \rightarrow p_i(x)$ is recursive.
- (4) $\forall i \ p_i \geq p_{i+1}$.

The best way to describe these functions p_1, p_2, \dots is to give a program for the machine N which, on inputs i and x , computes $p_i(x)$, (thus demonstrating that property (3) above holds).

Let f be computed by some machine M_k in space s_k . (In general, the space bound of the i -th TM will be denoted by s_i .) Here is the program for N :

begin

On input $\langle i, x \rangle$,
 Mark off $\log |x|$ tape.
 Using at most $\log |x|$ tape, try for each $j \leq i$ to
 determine if there is a y such that $M_j(y) \neq f(y)$. Mark
 all such j as "cancelled".

Let $A = \{j \leq i : j \text{ has not been marked as "cancelled"}\}$.

For $c := 1$ to ∞

For all $j \in A \cup \{k\}$

Try to simulate M_j on x using $\leq c$ of M_j 's tape cells.

If any of these simulations halts, halt and output $\max(c, (\log |x|))$.

end

Let us show that condition (1) holds: i.e., for all $i, p_i \in C$. Note that for all $j < i$ such that M_j does *not* compute f , we eventually cancel j , and thus for all large x , j gets cancelled during the first part of the computation on input $\langle i, x \rangle$. Thus, for all large x , during the second part of the computation on input $\langle i, x \rangle$, we are simulating *only* machines that compute f . Notice that the simulation never uses more than $ip_i(x)$ tape cells (assuming without loss of generality that, for all j , M_j can be simulated using at most js_j space). Notice also that the

simulation always us to successfully run some machine computing f . By the linear speed-up theorem, f can be computed in space p_i . (The reader may verify that, in addition, p_i is a space function.)

Conditions (2) and (4) are easily verified. That is left to the reader.

Now it will suffice to construct our function g so that the following two conditions are satisfied:

(a) $\forall i p_i \geq g$ a.e.

(b) For all space functions s_i such that $s_i(x) = \Omega(\log |x|)$,

$$\exists^\infty x s_i(x) < p_i(x) \implies \exists y > i s_i(y) < g(y).$$

Before we show that properties (a) and (b) hold, let us prove that they are sufficient to prove the claim.

It is clear (by condition (2)) that if f is computable in space s , then $\exists i s = \Omega(p_i)$. Since by (a), $p_i \geq g$ a.e., it follows that $s = \Omega(g)$.

Conversely, let s be a space function, $s(x) = \Omega(\log x)$, such that f is not computable in space s . We need to show that, for all k , $ks(x) < g(x)$ for infinitely many x . By the linear speed-up theorem, we know that f is not computable in space ks . It follows from (2) that $\forall i \exists^\infty x ks(x) < p_i(x)$. There are infinitely many machines M_{j_1}, M_{j_2}, \dots that have space complexity ks . (This is a property of most reasonable indexing systems; assume without loss of generality that we are using some such “reasonable” indexing.) That is, for all x , $ks(x) = s_{j_1}(x) = s_{j_2}(x) = \dots$. Thus $\forall r \forall i \exists^\infty x s_{j_r}(x) < p_i(x)$. By property (b), $\forall r \exists y > j_r s_{j_r}(y) < g(y)$. Since $ks = s_{j_r}$, it follows that $ks(y) < g(y)$ for infinitely many y .

Now that we know that (a) and (b) are sufficient, let us show how to compute g .

Begin

On input x

Mark off $\log |x|$ space.

For $i := 1$ to $\log |x|$

Attempt to determine (using at most $\log |x|$ space) if there is any y such that $i < y < x$ such that $s_i(y) < g(y)$. (Call any such i “cancelled”.)

Choose the least uncanceled i such that $s_i(x) < p_i(x)$, and cancel i and set $g(x) = p_i(x)$. (I.e., output $p_i(x)$.)

(If there is no such i , set $g(x) = p_{\log |x|}(x)$.)

End

To verify that (b) holds, let us assume that $\exists^\infty x s_i(x) < p_i(x)$. We need to show that there is some $y > i$ such that $s_i(y) < g(y)$. Let R be the set of all $j < i$ that ever get cancelled. It can be verified that all $j \in R$ get cancelled, using at most k tape cells, for some $k \in \mathbb{N}$. Choose x so that $k < \log |x|$ and

$x > i$ and $s_i(x) < p_i(x)$. (By assumption, such an x exists.) On input x , either i is already cancelled (in which case there is some $y > i$ such that $s_i(y) < g(y)$), or i will be the least uncanceled index such that $s_i(x) < p_i(x)$ and we will set $g(x) = p_i(x) > s_i(x)$, and we cancel i .

To verify that (a) holds, we need to show that for all i and for all large x , $p_i(x) \geq g(x)$. Again, let R be the set of all $j < i$ that ever get cancelled. For all large x , it can be verified on input x that everything in R gets cancelled, and thus, for all large x , there is some $j > i$ such that $g(x) = p_j(x)$. Since, by property (4), $j > i \implies p_j(x) \leq p_i(x)$, we have that for all large x , $g(x) \leq p_i(x)$.

That completes the proof.

The only English-language reference I have found for this result is: Leonid A. Levin, *Computational Complexity of Functions*, in Boston University Technical Report BUCS-TR-85-005, 1985. This is a one-page partial translation of the original paper: Leonid A. Levin, *Complexity of Algorithms and Computations*, Ed. Kosmidiadi, Maslov, Petri, "Mir", Moscow, 1974, 174–185. This (Russian) paper seems to be the only place that the proof has been published. Similar (although somewhat weaker and much messier) results may be found in: A. R. Meyer and K. Winklmann, *The Fundamental Theorem of Complexity Theory, (preliminary version)*, in Ed. J. W. DeBakker and J. van Leeuwen, *Mathematical Center Tracts 198* (1979), 97–112. Much of the proof in this handout is based on proofs in Meyer and Winklmann.