MLT Notes 1

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1 Notation and Definitions

Definition 1. Fix a differentiable convex function $\phi : \mathbb{R}^k \to \mathbb{R}$. The Bregman divergence from $x \in \mathbb{R}^k$ to $y \in \mathbb{R}^k$ generated by ϕ is

$$B_{\phi}(x,y) = \phi(x) - \phi(y) - \langle x - y, \nabla \phi(y) \rangle$$

where $\langle x, y \rangle$ denotes the dot product $\sum_{i=1}^k x_i y_i$, and $\nabla \phi(y)$ is the gradient (vector of partial derivatives) of ϕ at y.

Definition 2. Let us write $[k] = \{1, \ldots, k\}$, and let us denote the probability simplex by $\Delta_k = \{x \in \mathbb{R}^k \mid \sum_{i=1}^k x_i = 1 \text{ and } \forall i \, x_i \geq 0\}$. Fix a loss function $\ell : [k] \times \Delta_k \to \mathbb{R}$, and let

$$L(p,q) = \sum_{i=1}^{k} p_i \ell(i,q)$$

be its associated *risk*, and let

$$\underline{L}(p) = \inf_{q} L(p,q)$$

be its entropy. A loss function is called proper if for all $p, q \in \triangle_k$

$$L(p,p) \leq L(p,q).$$

2 Results

Here are two results about proper losses and Bregman divergences.

Theorem 1 (Savage'75).

- 1. For any loss, the entropy \underline{L} is concave.
- 2. For every differentiable concave $\Lambda : \Delta_k \to \mathbb{R}$, there is a proper loss with entropy $\underline{L}(p) = \Lambda(p)$.

Proof. 1. Minimum of linear is concave.

2. In this proof we are following the common special-case notation for 2 outcomes, where outcomes are $\{0,1\}$ and distributions on these 2 outcomes are parametrised by the probability $q \in [0,1]$ of observing the outcome 1. Let

$$\ell(y,q) = \Lambda(q) + (y-q)\Lambda'(q)$$

Then

$$L(p,q) = \Lambda(q) + (p-q)\Lambda'(q)$$

Using concavity, we hence find that

$$L(p,q) \geq \Lambda(p) = L(p,p)$$

and hence ℓ is proper and $\underline{\mathbf{L}}(p) = \Lambda(p)$.

Theorem 2. Fix a differentiable convex $\phi : \mathbb{R}^d \to \mathbb{R}$, and let B_{ϕ} be the associated Bregman divergence. Then

- 1. Reflexivity: $B_{\phi}(x,x) = 0$
- 2. Non-negativity: $B_{\phi}(x,y) \geq 0$
- 3. Convexity: $B_{\phi}(x,y)$ is convex in x for each y.
- 4. Generalised Properness: $\mathbb{E}[X] = \arg\min_{y} \mathbb{E}[B_{\phi}(X, y)].$
- 5. Generalised Pythagorean Inequality: Fix a convex set $C \subseteq R^d$ and $y \in \mathbb{R}^d$, and let

$$\hat{y} = \arg\min_{\hat{y} \in C} B_{\phi}(\hat{y}, y)$$

Then for any $x \in C$ we have

$$B_{\phi}(x,\hat{y}) + B_{\phi}(\hat{y},y) \leq B_{\phi}(x,y)$$

Proof. 1. Homework 1, question 2(a).

- 2. Homework 1, question 2(b).
- 3. Homework 1, question 2(c).
- 4. Homework 1, question 4.
- 5. By the first order optimality condition for \hat{y} , we know that for all $x \in C$

$$\langle x - \hat{y}, \nabla_{\hat{y}} B_{\phi}(\hat{y}, y) \rangle \ge 0$$
 (1)

and since $\nabla_{\hat{y}} B_{\phi}(\hat{y}, y) = \nabla \phi(\hat{y}) - \nabla \phi(y)$ we have

$$\langle x - \hat{y}, \nabla \phi(\hat{y}) - \nabla \phi(y) \rangle \geq 0$$

It remains to show

$$\underbrace{\phi(x) - \phi(\hat{y}) - \langle x - \hat{y}, \nabla \phi(\hat{y}) \rangle}_{B_{\phi}(x,\hat{y})} + \underbrace{\phi(\hat{y}) - \phi(y) - \langle \hat{y} - y, \nabla \phi(y) \rangle}_{B_{\phi}(\hat{y},y)} \ \leq \ \underbrace{\phi(x) - \phi(y) - \langle x - y, \nabla \phi(y) \rangle}_{B_{\phi}(x,y)}$$

that is

$$\langle x - \hat{y}, \nabla \phi(y) - \nabla \phi(\hat{y}) \rangle \le 0$$

which is equivalent to (1).